

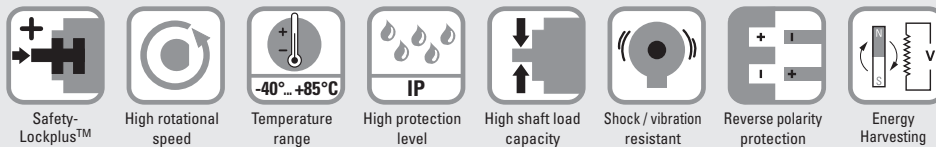
Absolute encoders – multiturn

| | | |
|--|-----------------------------|------------|
| Standard electronic multiturn, magnetic | Sendix M5863 (shaft) | SSI |
|--|-----------------------------|------------|



The Sendix M58 with Energy Harvesting Technology is an electronic multiturn encoder without gear and without battery – in the standard format with 58 mm flange.

High robustness and high resolution make this encoder the ideal device for use in demanding applications.



Highest robustness

- Sturdy bearing construction in Safety-Lockplus™ design for particularly high resistance.
- Extra large bearings.
- Mechanically protected shaft seal.
- Wide temperature range -40 °C ... +85 °C.
- Without gear and without battery, thanks to the Energy Harvesting technology.

Application oriented

- Angular measurement deviation $\pm 0,5^\circ$.
- Repeat accuracy $\pm 0,2^\circ$.
- Short control cycles, clock frequency with SSI up to 2 MHz.
- Max. resolution 38 bit (14 bit ST + 24 bit MT).

| Order code | 8.M5863 | .XX2X.XXX2 |
|--|---|--|
| Shaft version | Type | a b c d e f g |
| a Version | 3 = clamping flange, IP65, \varnothing 58 mm [2.28"] 4 = synchro flange, IP65, \varnothing 58 mm [2.28"] | d Type of connection 2 = radial cable, 1 m [3.28'] PUR B = radial cable, special length PUR *) 4 = radial M12 connector, 8-pin |
| b Shaft ($\varnothing \times L$), with flat | 1 = \varnothing 6 x 12.5 mm [0.24 x 0.49"] 5 = \varnothing 10 x 20 mm [0.39 x 0.79"] | e Code B = SSI, binary G = SSI, gray |
| c Interface / supply voltage | 2 = SSI / 10 ... 30 V DC | f Resolution (singleturn) A = 10 bit ST 2 = 12 bit ST 3 = 13 bit ST 4 = 14 bit ST |
| | | g Resolution (multiturn) 2 = 12 bit MT 6 = 16 bit MT A = 20 bit MT 4 = 24 bit MT |
| | | <i>Optional on request</i> - Ex 2/22 (only for connection type 4) |

| Mounting accessory for shaft encoders | | Order no. |
|---------------------------------------|--|-----------------------------|
| Coupling | Bellows coupling \varnothing 19 mm [0.75"] for shaft 10 mm [0.39"] | 8.0000.1102.1010 |
| Cables and connectors | | Order no. |
| Preassembled cables | M12 female connector with coupling nut, 8-pin, A coded, straight single ended 2 m [6.56'] PUR cable | 05.00.6051.8211.002M |
| Connectors | M12 female connector with coupling nut, 8-pin, A coded, straight (metal) | 05.CMB 8181-0 |

Further Kübler accessories can be found at: kuebler.com/accessories
Further Kübler cables and connectors can be found at: kuebler.com/connection-technology

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Technical data

Mechanical characteristics

| | | |
|--|-------------------------------------|---|
| Maximum speed | | 4000 min ⁻¹ 2000 min ⁻¹ (continuous) |
| Starting torque at 20 °C [68 °F] | | < 0.01 Nm |
| Shaft load capacity | radial axial | 80 N 40 N |
| Weight | | approx. 0.2 kg [7.06 oz] |
| Protection acc. to EN 60529/DIN 40050-9 | | IP65 |
| Working temperature range | | -40 °C ... +85 °C [-40 °F ... +185 °F] |
| Materials | shaft flange housing cable | V2A aluminum zinc die-cast PUR |
| Shock resistance acc. to EN 60068-2-27 | | 5000 m/s ² , 4 ms |
| Vibration resistance acc. to EN 60068-2-6 | | 300 m/s ² , 10 ... 2000 Hz |

Electrical characteristics

| | | |
|--|--|-------------------|
| Supply voltage | | 10 ... 30 V DC |
| Current consumption (no load) | | max. 30 mA |
| Reverse polarity protection of the supply voltage | | yes |
| Short-circuit proof outputs | | yes ¹⁾ |

SSI interface

| | | |
|--|--|------------------------|
| Output driver | | RS485 transceiver type |
| Permissible load / channel | | max. +/- 30 mA |
| Signal level | HIGH LOW with I _{Load} = 20 mA | typ 3.8 V typ 1.3 V |
| Resolution singleturn | | 10 ... 14 bit |
| Angular measurement deviation ²⁾ | | ±0,5° |
| Repeat accuracy | | ±0.2° |
| Number of revolutions (multiturn) | | max. 24 bit |
| Code | | binary or gray |
| SSI clock rate | | 50 kHz ... 2 MHz |
| Data refresh rate | | 2 ms |
| Monoflop time | | ≤ 15 μs |

Note: If the clock cycle starts within the monoflop time a second data transfer begins with the same data. If the clock cycle starts after the monoflop time the cycle begins with the new values. The update rate is dependent on the clock speed, data length and monoflop time.

SET input

| | | |
|---|-------------|---|
| Input | | active HIGH |
| Input type | | comparator |
| Signal level | HIGH LOW | min. 60 % of +V, max: +V max. 30 % of +V |
| Input current | | < 0.5 mA |
| Min. pulse duration (SET) | | 10 ms |
| Input delay | | 1 ms |
| New position data readable after | | 1 ms |
| Internal processing time | | 200 ms |

The encoder can be set to zero at any position by means of a HIGH signal on the SET input. Other preset values can be factory-programmed. The SET input has a signal processing time of approx. 1 ms, after which the new position data can be read via SSI. Once the SET function has been triggered, the encoder requires an internal processing time of typ. 200 ms; during this time the supply voltage must not be switched off.

The SET function should be carried out whilst the encoder is at rest.

The number of preset value writing cycles is limited to 10,000.

If this input is not used, it should be connected to 0 V (Encoder ground GND) in order to avoid interferences.

DIR input

Direction input: A HIGH signal switches the direction of rotation from the default cw to ccw. This inverted function can also be factory-programmed.

If this input is not used, it should be connected to 0 V (Encoder ground GND) in order to avoid interferences.

| | | |
|----------------------------------|--|------|
| Response time (DIR input) | | 1 ms |
|----------------------------------|--|------|

Power-ON

After Power-ON the device requires a time of approx. 150 ms before valid data can be read.

Hot plugging of the encoder should be avoided.

Approvals

| | | |
|--|---|---|
| UL compliant in accordance with | | File no. E224618 |
| CE compliant in accordance with | EMC Directive RoHS Directive ATEX Directive | 2014/30/EU 2011/65/EU 2014/34/EU (for Ex 2/22 variants) |

1) Short circuit proof to 0 V or to output when supply voltage correctly applied.

2) Over the whole temperature range.

Absolute encoders – multitrurn

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|---|-----------------------------|------------|

Terminal assignment

| Interface | Type of connection | Features | Cable (isolate unused cores individually before initial start-up) | | | | | | | | | |
|-----------|--------------------|----------|---|-----|----|----|----|----|----|-----|-----|--------|
| 2 | 2, B | SET, DIR | Signal: | 0 V | +V | C+ | C- | D+ | D- | SET | DIR | ⊥ |
| | | | Core color: | WH | BN | GN | YE | GY | PK | BU | RD | shield |

| Interface | Type of connection | Features | M12 connector, 8-pin | | | | | | | | | |
|-----------|--------------------|----------|----------------------|-----|----|----|----|----|----|-----|-----|----|
| 2 | 4 | SET, DIR | Signal: | 0 V | +V | C+ | C- | D+ | D- | SET | DIR | ⊥ |
| | | | Pin: | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | PH |

- +V: Supply voltage encoder +V DC
- 0 V: Supply voltage encoder ground GND (0 V)
- C+, C-: Clock signal
- D+, D-: Data signal
- SET: Set input
- DIR: Direction input
- PH ⊥: Plug connector housing (shield)

Top view of mating side, male contact base



M12 connector, 8-pin

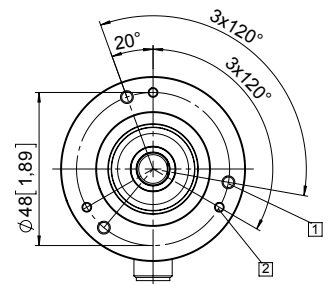
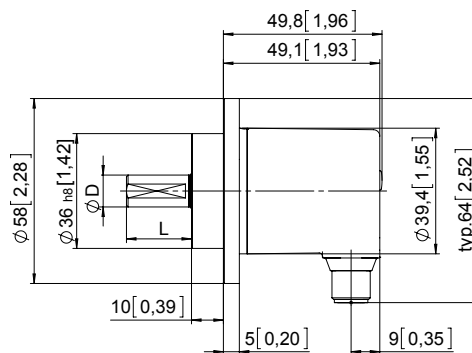
Dimensions

Dimensions in mm [inch]

Clamping flange, ø 58 [2.28] Flange type 3

- 1 3 x M4
- 2 3 x M3

| D | Fit | L |
|-----------|-----|-------------|
| 6 [0.24] | h7 | 12.5 [0.49] |
| 10 [0.39] | f7 | 20 [0.79] |



Synchro flange, ø 58 [2.28] Flange type 4

- 1 3 x M4, 10 [0.39] deep

| D | Fit | L |
|-----------|-----|-------------|
| 6 [0.24] | h7 | 12.5 [0.49] |
| 10 [0.39] | f7 | 20 [0.79] |

